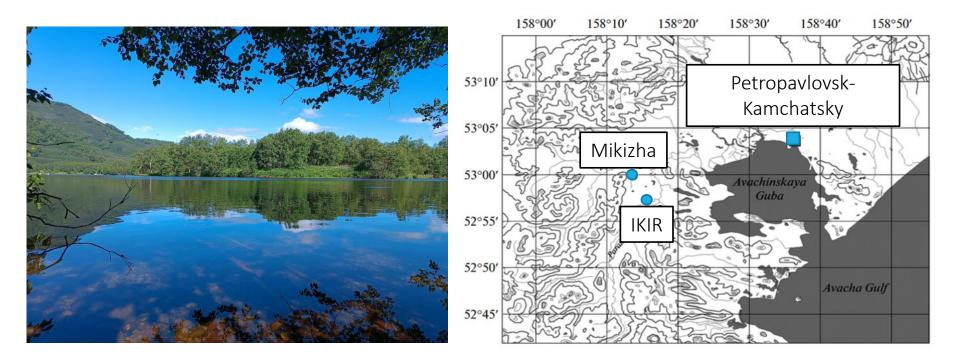


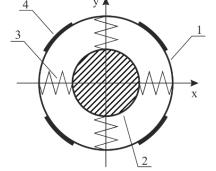
Localization of acoustic emission sources according to the data of a distributed system of combined receivers

SHCHERBINA A.O., <u>SOLODCHUK A.A.</u>, VASKIN V.A., TORGONSKYI V.E.

# ACOUSTIC SIGNAL RECORDING



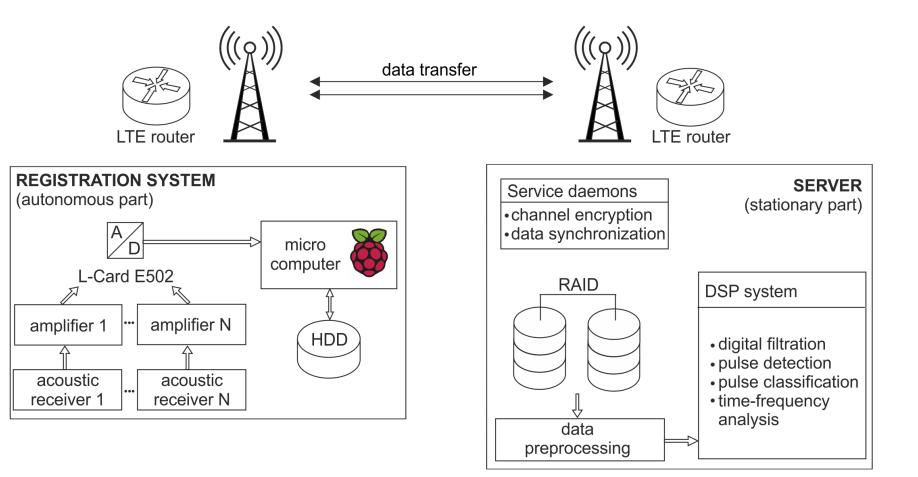




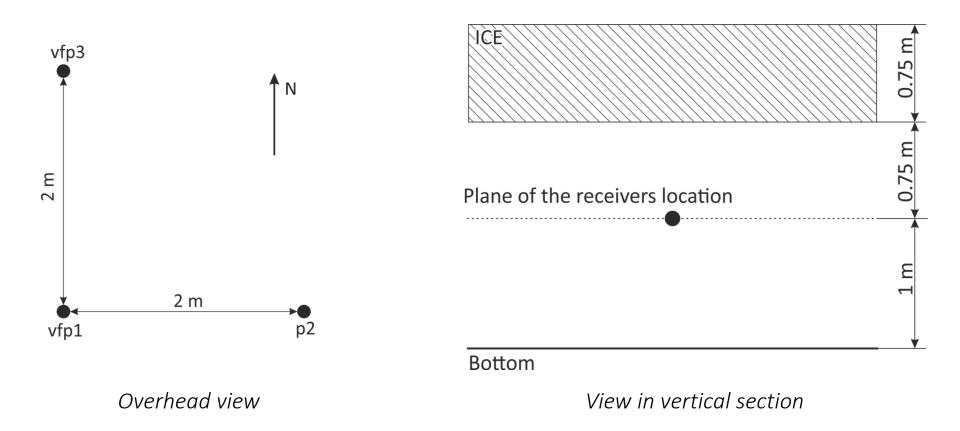
- 1 receiver body,
- 2 inertial mass,
- 3 elastic elements,
- 4 pressure receiver components

Measured values: P,  $\nabla$ Px,  $\nabla$ Py,  $\nabla$ Pz Frequency range: 100 Hz – 10 kHz

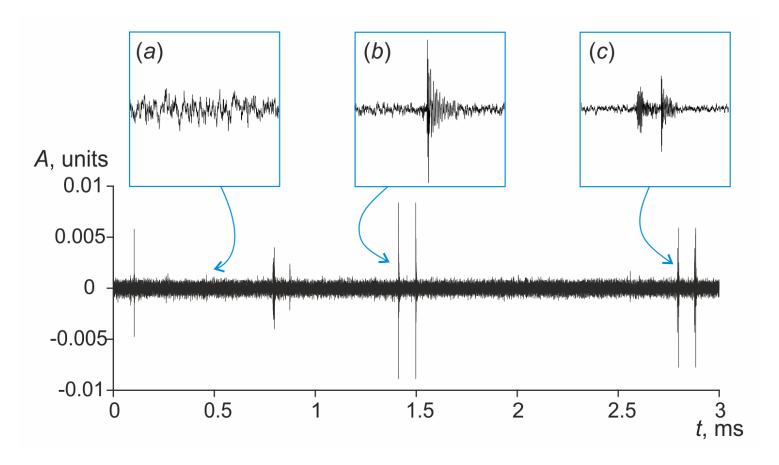
### **REGISTRATION SYSTEM**



### RECEIVER LOCATION DIAGRAM (February 13, 2023)

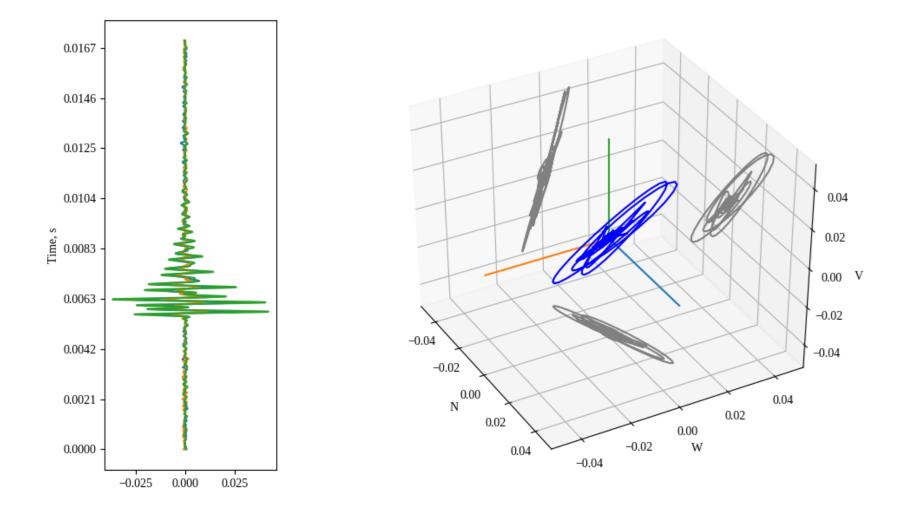


## **ACOUSTIC EMISSION SIGNAL**

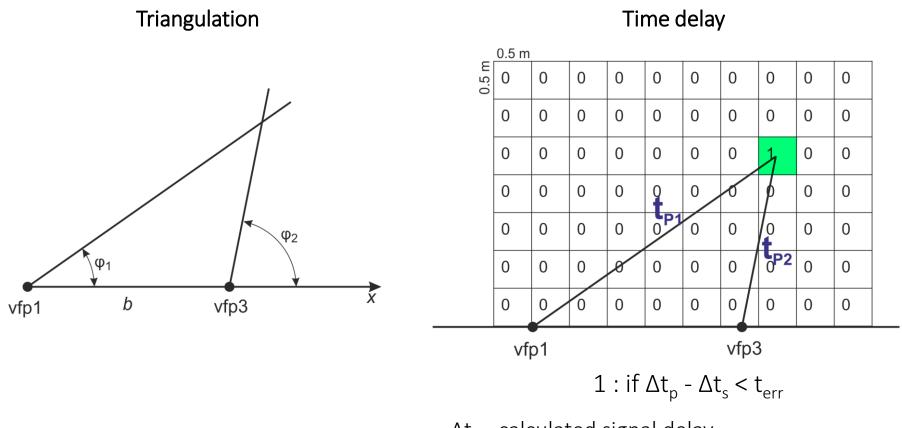


Acoustic emission signal fragment: (a) – noise; (b), (c) – pulses.

# ACOUSTIC PULSE



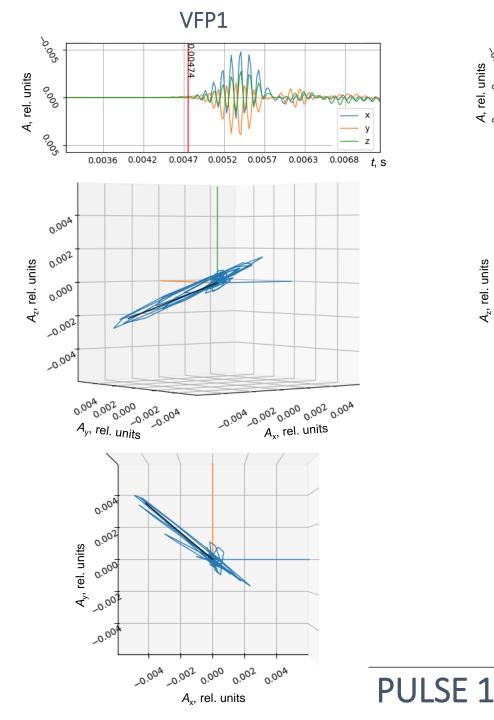
# LOCALIZATION METHODS

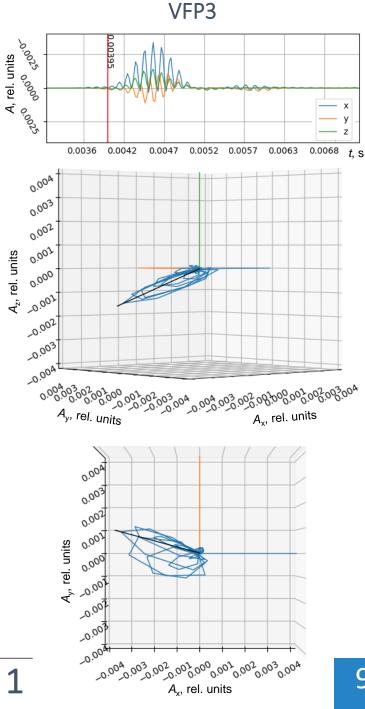


 $\Delta t_p$  - calculated signal delay,

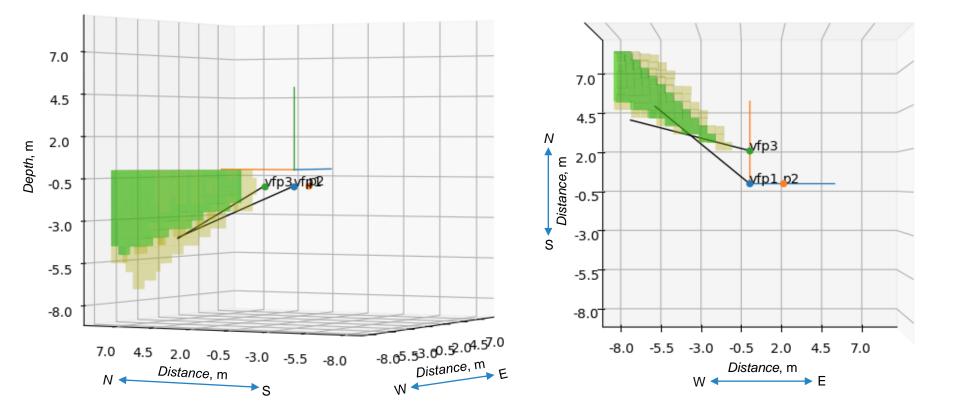
 $\Delta t_{s}$  - measured signal delay,

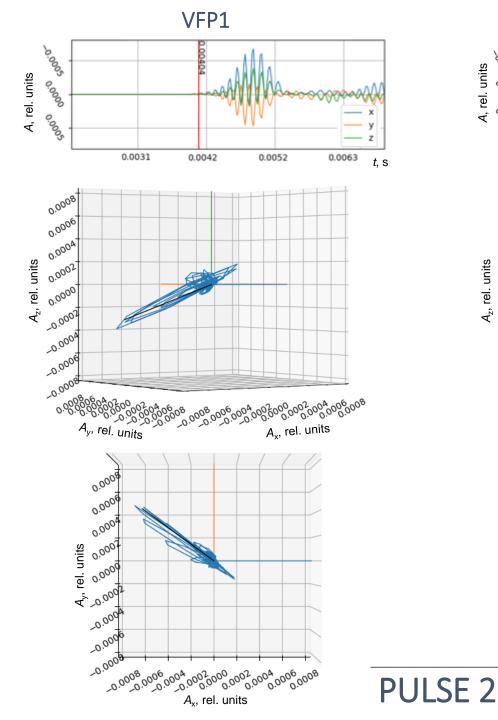
 $t_{err}$  - permissible error (corresponds to the time during which the wave propagates 0.25 m)

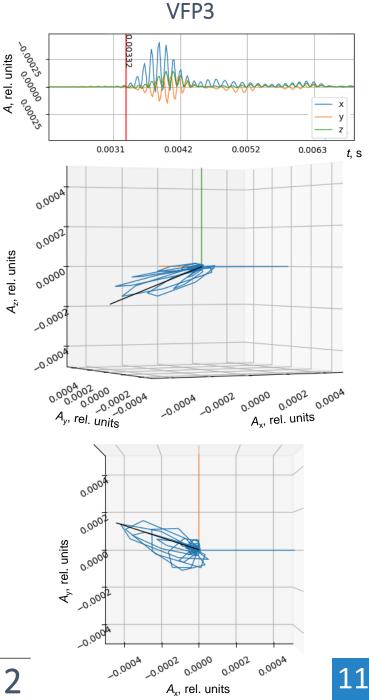




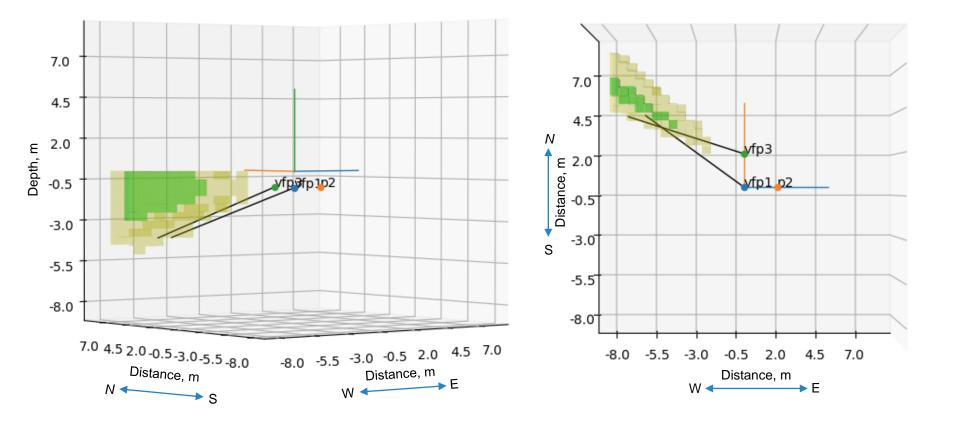
#### LOCALIZATION RESULT



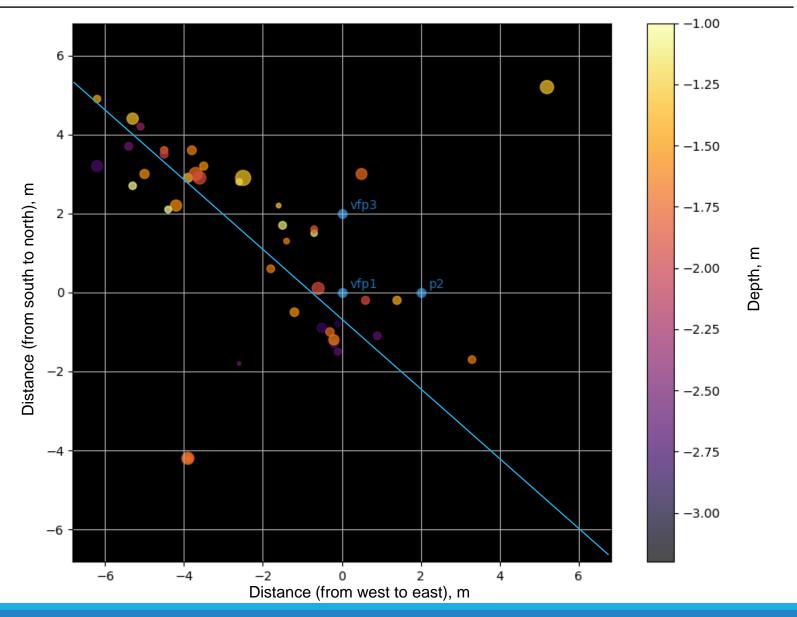




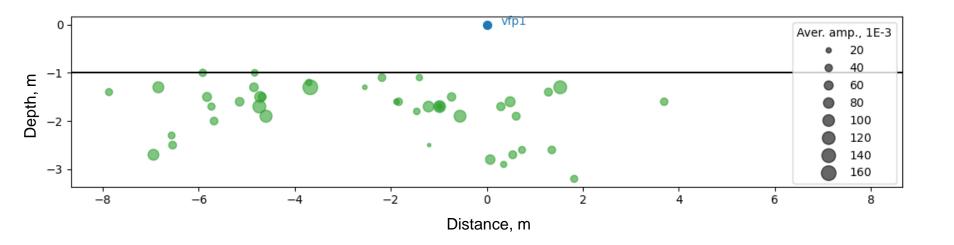
### LOCALIZATION RESULT



## **RESULTS: SOURCE DISTRIBUTION**



## **RESULTS: SOURCE DISTRIBUTION**



Duration of the record	105 minutes
Number of pulses	43
Maximum depth	3.2 ± 0.25 m
Maximum distance	8 ± 0.25 m



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